# GP-PRO/PBIII for Windows Device/PLC CONNECTION MANUAL ADDITIONAL MANUAL

# Yokogawa Electric Corporation FCN/FCJ Series



## Reading the GP-PRO/PBIII Device/PLC Connection Manual

This document is designed as an addition to the latest GP-PRO/PBIII for Windows Device/PLC Connection manual's Yokogawa Electric Corporation data.

When connecting a Factory Gateway unit, please substitute the words "Factory Gateway" for this document's "GP/GLC/ST".

## Installation

This CD-ROM includes all the protocol files required by the GP/GLC to communicate with a Yokogawa Electric Corporation FCN/FCJ Series PLC. Also, you will need to have one or more of the following software applications installed. <u>The screen</u> and data transfer files included in the CD-ROM must be installed in each of those applications. For information regarding installing the software, refer to that software's Operation Manual.

#### Software Applications

- GP-PRO/PBIII for Windows Ver. 7.0
- Pro-Server with Pro-Studio for Windows Ver. 4.1 \*1
- 1) Be sure to confirm that the required software application is installed in your PC prior to starting installation.
- 2) Double-click the CD-ROM's "FCNFCJMB.exe" file to start the installation process.
- 3) Once the installation program starts, follow the instructions given to install the protocol files.



When using Yokogawa Electric Corporation Stardom Series PLCs, be sure to select [Others] - [Yokogawa Electric FCN/FCJ ModbusRTU 1:n] for the "Device/PLC Type".

<sup>\*1</sup> When using the Factory Gateway unit, GP-Web Ver. 1.0 or later or GP-Viewer Ver. 1.0 or later, be sure to select "Pro-Server with Pro-Studio for Windows" as the "Destination Folder".

#### 2.8 **Yokogawa Electric**

**System Structure** 2.8.1

> The following describes the system structure for connecting the GP to Yokogawa Electric Corp. PLCs.

**Seference** The Cable Diagrams mentioned in the following tables are listed in the section titled "2.8.2 Cable Diagrams".

#### **FACTORY ACE Series/FA500** (using Link I/F)

CPU	Link I/F	Cable Diagram	Cables	GP
	PC Link Module	4	;	
FA500	LC01-ON	RS-232C	Digital's GP-410-IS00-O (5m)	
		(Cable Diagram 1)		
	LC02-ON	RS-232C	RS-232C	
		(Cable Diagram 1)	Digital's	
			GP410-IS00-O (5m)	CD Sorios
		RS-422		GF JEIIES
		(Cable Diagram 2)		
		RS-422 1:n		
		communication *1		
		(Cable Diagram 3)		

\* 1 1:n Communication

The system structure of 1:n communication for Yokogawa PLCs (FA500), or equipment supporting its protocol (n#), and a GP unit (1) used as an upper link protocol is described here.



<sup>(</sup>See next page)

(Continued from previous page)

\* FA500 and equipment (Digital Indicating Controller, <UT37/38/2000> and Recorder, <µR-Series>...etc) supporting the same protocol are hereafter referred to as *PA Equipment*.

- Be sure to use only one GP in the system.
- In the Link above, maximum 32 PA Equipment can be connected to one GP.
- When Sequence Control is not required, a PLC is not needed.
- Using the method above, Unit No. s 1~16 can be setup; a Unit No. of 17 or higher cannot be used.



Wherever RS-422 appears in the table, RS-485 can be used on the PLC.

#### ■ FACTORY ACE Series/FA-M3 (using Link I/F)

СРИ	Link I/F	Cable Diagram	Cables	GP
	PC Link	4	 	
F3SP10-0N	F3LC01-1N	RS-232C		
		(Cable Diagram 4)		
F3SP20-0N, F3SP21-0N,	F3LC11-1N	RS-232C		
F3SP25-2N, F3SP28-3N,	F3LC11-1F	(Cable Diagram 4)		
F3SP30-0N, F3SP35-5N,	F3LC12-1F			
F3SP38-6N, F3SP53-4H,	F3LC11-2N	RS-422 (4-wire type)		
F3SP58-6H, F3FP36-3N,		(Cable Diagram 2)		
F3SP28-3S, F3SP38-6S,		RS-422 (2-wire type)		GP Series
F3SP53-4S, F3SP58-6S,		(Cable Diagram 5)		
F3SP59-7S	F3LC11-2N	RS-422, 4-wire type		•
		1:n communication *1		
		(Cable Diagram 3)		
		RS-422, 2-wire type		
		1:n communication		
		(Cable Diagram 6)		

#### \*11:n Communication

The system structure of 1:n communication for Yokogawa PLCs (**FA-M3**), or equipment supporting its protocol (n#), and a GP unit (1) used as an upper link protocol is described here.



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- \* FA-M3 and equipment (Digital Indicating Controller, <UT37/38/2000> and Recorder, <mR-Series>...etc) supporting the same protocol is referred to as *PA Equipment*, below.
- Be sure to use only one GP in the system.
- In the Link above, maximum 32 PA Equipment can be connected to one GP.
- When Sequence Control is unnecessary, the system structure can be created without the PLC.
- Using the method above, Unit No.s 1~16 can be setup, however a Unit No. of 17 or more cannot be used.



#### Wherever RS-422 appears in the table, RS-485 can be used on the PLC.

CPU	Cables	GP
	← →	
F3SP21-0N, F3SP25-2N,	Yokogawa's cable for	
F3SP28-3N, F3SP35-5N,	programming tool KM11-	
F3SP38-6N, F3SP53-4H,	2N*A	
F3SP58-6H, F3SP28-3S,		GP Series
F3SP38-6S, F3SP53-4S,		
F3SP58-6S, F3SP59-7S		

**FACTORY ACE Series/FA-M3** (CPU Direct Connection)



Two GP units cannot be connected at the same time using the PC Link I/F.

## STARDOM Standalone Controller FCN/FCJ Series (When using Yokogawa Electric FCN/FCJ ModbusRTU 1:n Protocol)

CPU	Link I/F	Cable Diagram	Target Unit
		<	
	COM Port on CPU	RS-232C (Cable Diagram 7)	
FCN	RS232C Port 1 or 2 on NFLR111 RS232C Communication Module	RS-232C (Cable Diagram 8)	
		RS-422 (4-wire) (Cable Diagram 9)	GP/GLC/ST Series
	Communication Terminal Block on NFLR121	RS-422 (4-wire) 1:n Communication (Cable Diagram 10)	Factory Gateway
	RS422/RS485 Communcation Module	RS-422 (2-wire) (Cable Diagram 11)	
		RS-422 (2-wire) 1:n Communication (Cable Diagram 12)	
FCJ	COM Port 1 or 2 on CPU	RS-232C (Cable Diagram 7)	GP/GLC/ST Series, Factory Gateway

## STARDOM Standalone Controller FCN/FCJ Series (When using Yokogawa Electric FACTORY ACE 1:1, FACTORY ACE 1:n Protocol)

CPU	Link I/F	Cable Diagram	Target Unit
		<	
FCN	COM Port on CPU	RS-232C	GP/GLC/ST Series,
FCJ	COM Port 1 or 2 on CPU	(Cable Diagram 4)	Factory Gateway

## 2.8.2 Cable Diagrams

The cable diagrams illustrated below and the cable diagrams recommended by Yokogawa Electric may differ, however, using these cables for your PLC operations will not cause any problems.



Ground your PLC's FG terminal according to your country's applicable standard. For details, refer to the corresponding PLC manual.



 Connect the FG line of the Shield cable to either the GP or PLC, depending on your environment. When using a connector hood and grounding the FG line, be sure to use an electrical conductor. The following connection diagrams show examples for connecting a shielded cable to the PLC.

- For the RS-232C connection, use a cable length less than 15m.
- If a communications cable is used, it must be connected to the SG (signal ground).
- For the RS-422 connection, refer to Yokogawa's PLC manual for the cable length.



#### Cable Diagram 1 (RS-232C)

#### Cable Diagram 2 (RS-422)

• When using Digital's RS-422 connector terminal adapter GP070-CN10-0





#### • When using Digital's RS-422 Cable, GP230-IS11-0



- When making your own connections, we recommend using Hitachi Densen's CO-SPEV-SB(A)3P\*0.5SQ cable.
- When connecting the #9 and #10 pins in the GP Serial I/F, a termination resistance of  $100\Omega$  is added between RDA and RDB.
- When connecting an RS422 cable, length can be up to 600 meters.

#### Cable Diagram 3 (RS-422)

The diagrams below are examples of wire connections on both ends of the GP and PLC. Setup the termination resistors on both ends of the equipment, as illustrated.



- Be careful as the reading of the A signal and B signal is opposite on the GP and the LC02-0N (PLC).
- Make the PC Link I/F Station Number from 2 to 32.
- Setup the PA unit connected to the GP using different Unit Numbers. An error will develop if multiple PA units are setup using the same Unit Number. When an error occurs, the error message "Data Reception Error occurs (02:FD:\*\*)" (\*\* indicates the unit No.) will appear.
- Setup the GP (1) and PA units (n#) with the same Communication Settings.







When connecting the #9 and #10 pins in the GP Serial I/F, a termination resistance of  $100\Omega$  is added between RDA and RDB.



#### Cable Diagram 5 (RS-422)





• When using Digital's RS-422 cable, GP230-IS11-0



• When making your own cable connections





#### Cable Diagram 6 (RS-422)

• When using Digital's RS-422 connector terminal adapter GP070-CN10-0

Note:

- If the connection is terminated while 2-wire type communication is being carried out, use the 2-wire termination resistance switch on the PC link module (F3LC11-2N).
  - The names of the poles A and B are reversed between the GP and the PLC.

#### Cable Diagram 7 (RS-232C)





#### • When using ST401 unit.



#### Cable Diagram 8 (RS-232C)

• When connecting to a GP.



• When using ST401 unit.



#### Cable Diagram 9 (RS-422)

• When using Digital's RS-422 connector terminal adapter GP070-CN10-0



• When making your own cable connections





Cable Diagram 10 (RS-422)

• When using Digital's RS-422 connector terminal adapter GP070-CN10-0







• When making your own cable connections





Cable Diagram 12 (RS-422)

• When using Digital's RS-422 connector terminal adapter GP070-CN10-0



• When making your own cable connections





#### **Supported Devices** 2.8.3

The following describes the range of devices supported by the GP.

Г

Device	Bit Address	Word Address	Partic	ulars	
Input Relay	X00201 ~ X61164	X00201 ~ X61149	÷16+1)	*1 *2	
Output Relay	Y00201 ~ Y61164	Y00201 ~ Y61149	÷16+1)	*1 *2	
Internal Relay	10001 ~ 12048	10001 ~ 12033	÷16+1)	*2	
Joint Relay	E0001 ~ E2048	E0001 ~ E2033	÷16+1)		
Special Relay	M001 ~ M512	M001 ~ M497	÷16+1)	*2 *3	
Link Relay	L0001 ~ L1024	L0001 ~ L1009	<u>÷16∓]</u> )	*2 *3	
Timer (contact)	T001 ~ T256			*2	
Counter (contact)	C001 ~ C256			*2	I /LI
Timer (current value)		TP001 ~ TP256		*2	L/11
Timer (setup value)		TS001 ~ TS256		*2	
Counter (current value)		CP001 ~ CP256		*2	
Counter (setup value)		CS001 ~ CS256		*2	
Data Register		D0001 ~ D2048	Bit] 5]	*2	
Common Register		B0001 ~ B2048	Bit] 5]	*2	
Special Register		Z001 ~ Z128	Bit] 5]	*2*3	
Link Register		W0001 ~ W1024	Bit] 5]	*2*3	

**FA500** (1:1 communication)

Setup System Area here.

\* 1 The value of the terminal number (bit), 01~49, of the last two digits for the Input Relay and Output Relay can only be a multiple of 16 + 1.

E.g. For X00201

\* 2 Write the CPU Number  $(1 \sim 4)$  in front of the device name.

E.g. For Internal Relay 10001, CPU #3:

\* 3 Cannot perform data write.

Device	Bit Address	Word Address	Particulars	;
Input Relay	X00201 ~ X61164	X00201 ~ X61149	÷16+]) *1*2	
Output Relay	Y00201 ~ Y61164	Y00201 ~ Y61149	÷16+) *1*2	1
Internal Relay	10001 ~ 12048	10001 ~ 12033	÷16+]) *2	1
Joint Relay	E0001 ~ E2048	E0001 ~ E2033	÷16+1)	1
Special Relay	M001 ~ M512	M001 ~ M497	÷16+]) *2*3	1
Link Relay	L0001 ~ L1024	L0001 ~ L1009	÷16+]) *2*3	1
Timer (contact)	T001 ~ T256		*2	1
Counter (contact)	C001 ~ C256		*2	
Timer (current value)		TP001 ~ TP256	*2	
Timer (setup value)		TS001 ~ TS256	*2	1
Counter (current value)		CP001 ~ CP256	*2	1
Counter (setup value)		CS001 ~ CS256	*2	1
Data Register		D0001 ~ D2047	Bit 5 *2	1
Common Register		B0001 ~ B2047	Bit 5 *2	1
Special Register		Z001 ~ Z128	Bit ] 5] *2*3	]
Link Register		W0001 ~ W1024	Bit 5 *2*3	1

## **FA500** (1:n communication)

Setup System Area here.

\* 1 When setting Word Address, set the value of the terminal number, 01~49, of the last two digits for the Input Relay and Output Relay to a multiple of 16+1.

E.g. For X00201

\* 2 Write the CPU Number (1~4) in front of the device name.

E.g. For Internal Relay I0001, CPU #3:

\* 3 Cannot perform data write.



When setting tags up in GP-PRO/PBIII for Windows, the PLC Station number can be specified during address Input. If a station number is not indicated, it automatically uses the previously entered station number. (The initial default value is 1.)



l a

## **FA-M3** (1:1 Communication)

Device	Bit Address	Word Address	Particulars	
Input Relay	X00201 ~ X71664	X00201 ~ X71649	<u>÷16+</u> ]) <sup>*1*2</sup>	
Output Relay	Y00201 ~ Y71664	Y00201 ~ Y71649	<u>÷16∓]</u> ) *1	
Internal Relay	100001 ~ 165535	100001 ~ 165521	<u>÷16+])</u>	
Joint Relay	E0001 ~ E4096	E0001 ~ E4081	<u>÷16+])</u>	
Special Relay	M0001 ~ M9984	M0001 ~ M9969	÷16+])	
Link Relay	L00001 ~ L78192	L00001 ~ L78177	<u>÷16+]</u> ) *	
Timer (contact)	T0001 ~ T3072		*2	
Counter (contact)	C0001 ~ C3072		*2	
Timer (current value)		TP0001 ~ TP3072		
Timer (setup value)		TS0001 ~ TS3072	*2	I /LI
Counter (current value)		CP0001 ~ CP3072		L/11
Counter (setup value)		CS0001 ~ CS3072	*2	
Data Register		D00001 ~ D65535	Bit] 5]	
		B00001 ~ B065536		
Filo Dogistor		B065537 ~ B131072	⊡#]5] *3*4	
r lie Regisiel		B131073 ~ B196608		
		B196609 ~ B262144		
Joint Register		R0001 ~ R4096	Bit ] 5]	
Special Register		Z001 ~ Z1024	Bit] 5]	
Link Register		W00001 ~ W74096	Bit ] 51 *5*6	

(See next page)

\*1 The value of the terminal number (bit), 01~49, of the last two digits for the Input Relay and Output Relay can only be a multiple of 16 +1.

E.g. For X00201

$$\begin{array}{c} X & \underline{002} & \underline{01} \\ Slot & No. \end{array} \xrightarrow{1} \begin{array}{c} U \\ \Box \end{array} \begin{array}{c} Terminal & No. \end{array}$$

- \*2 Cannot perform data write.
- \*3 File registers are each 65,535 words on your GP application.

You cannot extend over more than a single data "block" when performing the following features.

Be sure to set these features' settings so they are within a single data block.

- 1) "a-tag " settings
- 2) Performing Block read/write from Pro-Server
- 3) Designating the "Convert from" and "Convert to" address for the "Address Conversion" features
- \*4 When using a PC Link module, only Link Register up to B99999 can be used.
- \*5 Up to 4,096 link registers can be used.
- \*6 Enter Link Relay (L) and Link Register (W) data as follows:

(Ex.) When entering Link Relay "L71024" data.



Address (Link Relay: 0001 to 8192, Link Device: 0001 to 4096)
Link Number (0 to 7)
Device Name (Link Relay: L, Link Device: W)

The address data's left-most digit is the Link Number, and the next four digits are the address.

• Write the CPU Number (1~4) in front of the device name.



E.g. For Internal Relay I0001, CPU #3:



• The types of devices that can be used will vary depending on the type of PLC.

For detailed information refer to Yokogawa's Sequencer CPU manual.

FA-M3	(1:n	Communication)
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Setup System Area here.

Device	Bit Address	Word Address	Particulars	5
Input Relay	X00201 ~ X71364	X00201 ~ X71349	÷16+1) *1*2	
Output Relay	Y00201 ~ Y71364	Y00201 ~ Y71349	<u>÷16∓])</u> "	]
Internal Relay	10001 ~ 132768	10001 ~ 132753	<u>÷16∓]</u> )	
Joint Relay	E0001 ~ E4096	E0001 ~ E4081	<u>÷16∓]</u> )	
Special Relay	M0001 ~ M9984	M0001 ~ M9969	<u>÷16∓]</u>	]
Link Relay	L00001 ~ L72048	L00001 ~ L72033	<u>÷16∓l)</u>	
Timer (contact)	T0001 ~ T2047		*	2
Counter (contact)	C0001 ~ C2047		*	2
Timer (current value)		TP0001 ~ TP2047		L/H
Timer (setup value)		TS0001 ~ TS2047		
Counter (current value)		CP0001 ~ CP2047		
Counter (setup value)		CS0001 ~ CS2047		
Data Register		D0001 ~ D2047	Bitl 51	
File Register		B0001 ~ B2047	Bit ] 5]	
Joint Register		R0001 ~ R2047	Bit ] 5]	
Special Register		Z001 ~ Z1024	Bitl 51	
Link Register		W0001 ~ W11024	Bit ] 5] *	1

\*1 The value of the terminal number (bit), 01~49, of the last two digits for the Input Relay and Output Relay can only be a multiple of 16 +1.

E.g. For X00201





\*2 Cannot perform data write.

\*3A total of up to 4,096 link registers can be used.

• Write the CPU Number (1~4) in front of the device name.

E.g. For Internal Relay I0001, CPU #3:



The range of devices that can be used will vary depending on the type of PLC. For detailed information refer to the Yokogawa's Sequencer CPU manual.

• When running tag setup in GP-PRO/PBIII for Windows, the PLC Station number can be specified at address Input. If a station number is not indicated, it automatically uses the previously entered station number. (The initial default value is 1.)



## STARDOM Standalone Controller (When using Yokogawa Electric FACTORY ACE 1:1, FACTORY ACE 1:1 Protocol)

Register Image	Bit Address	Word Address	Particulars
Internal Relay	10001 ~ 132767	10001 ~ 32753	<u>÷16+</u> ])
Data Register		D00001 ~ D32767	Bit] 5]
File Register		B000001 ~ B032767	Bitl 51



• Set each device using a CPU number of 1.

## **STARDOM Standalone Controller (When using Yokogawa Elec**tric FCN/FCJ ModbusRTU 1:n Protocol)

		Setup S	ystem Area	here.
Device	Bit Address	Word Address	Note	
Coil	1:00001 to 31:09984	1:00001 to 31:09969	÷16+1	
Input Relay	1:10001 to 31:19984	1:10001 to 31:19969	÷16+1 *1	
Retain Register	1:4000100 to 16:4999915	1:40001 to 16:49999		L/H
Retain Register		17:40001 to 31:49999	Bit15 *2	
Input Register		1:30001 to 31:39999	Bit15 *1	

\*1 Read only. Write is not possible. If write is attempted, a Host Communication error (02:FB) will occur.

\*2 Node address 17 to 31's Bit Address designation becomes Bit15 operation.



• Address ranges depend on the type of PLC used. For details please refer to your PLC unit's manual.

#### When using Pro-Server:



When accessing via Pro-Server, be sure to define in advance Device Addresses to be accessed, and after creating project screens, Pro-Server must be used to import the symbols. For details, refer to your Pro-Server Operation Manual.



## When using Word Addresses

Bit Switch Settings [BS_001]	×
General Settings Shape/Color Label Extend	
Description Operation Bit Address	1
☐ Monitor	
Modbus Device Address	
Node No.: <u>1 [Station No:1]</u>	
Browser	
Place Cancel Help	
Designates the Designates the Designates the Device Address Address Bit Position	

## ■ When using Bit Addresses

## 2.8.4 Environment Setup

The following lists Digital's recommended PLC and GP communication settings. **FACTORY ACE Series** (using Link I/F RS-232C connection)

GP Setup		PC Link Modul	e Setup
Baud Rate	19200 bps	Baud Rate <sup>*1</sup>	19200 bps
Data Length	8 bits	Data Length	8 bits
Stop Bit	1 bit	Stop Bit	1 bit
Parity Bit	None	Parity Bit	None
Data Flow Control	ER Control		
Communication Format	RS-232C		
		Check Sum	No
		Specify End Character	Yes
		Protect Function	No
		Data Format Setup Switch	8 OFF
Unit No.	1	Station Number *2	1

\*1 The PC Link I/F F3LC11-1F can be communicated by 115.2kbps.

\*2 The PC Link I/F F3LC01-1N does not have this setting.

## **FACTORY ACE Series** (using Link I/F RS-422 connection)

GP Se	etup	PC Link Module/PA	Equipment Setup
Baud Rate (1:1 comm)	19200 bps	Baud Rate (1:1 comm)	19200 bps
Baud Rate (1:n comm)	9600 bps	Baud Rate (1:n comm)	9600 bps
Data Length	8 bits	Data Length	8 bits
Stop Bit	1 bit	Stop Bit	1 bit
Parity Bit	None	Parity Bit	None
Data Flow Control	ER Control		•
Communication Format (Select 4-wire type)	4-wire type		
Communication Format (Select 2-wire type)	2-wire type		
		Checksum	No
		Specify End Character	Yes
		Protect Function	No
		Data Format Setup Switch	8 OFF
Unit No. (1:1 comm)	FA-500: 2 FA-M3: 1	Station No. (1:1 comm)	FA-500: 2 FA-M3: 1
Unit No. (1:n comm)	Match with PC Link Module station No.	Station No. (1:n comm)	Set up so that all PA Equip., PC Link module No.s are different

GP Setup		CPU Communicatio	on Port Setup
Baud Rate	19200 bps	Baud Rate	19200 bps <sup>*1</sup>
Data Length	8 bits		
Stop Bit	1 bit		
Parity Bit	Even	Parity Bit	Even
Data Flow Control	ER Control		
Communication Format	RS-232C		
		PC Link Function	Use
		Check Sum	No
		Specify End Character	Yes
		Protect Function	No
Unit No.	1		•

## ■ FACTORY ACE Series (FA-M3 CPU Direct Connection)

\*1 For F3SP28-3N, F3SP38-6N, F3SP53-4H, F3SP58-6H, F3SP28-3S, F3SP38-6S, F3SP53-4S, F3SP58-6S and F3SP59-7S, a baud rate of 115200 bps is also available.

# ■ STARDOM Standalone Controller (When using Yokogawa Electric FACTORY ACE 1:1, FACTORY ACE 1:n Protocol)

GP Setu	р	CPU Communication	on Port Setup
Baud Rate	19200 bps <sup>*3</sup>	Baud Rate	19200 bps <sup>*1*3</sup>
Data Length	8 bits	Data Length	8 bits <sup>*1</sup>
Stop Bit	1 bit	Stop Bit	1 bit <sup>*1</sup>
Parity Bit	None	Parity Bit	None *1
Data Flow Control	ER Control		
Communication	RS-232C		
Format			
		Check Sum	No <sup>*2</sup>
		Specify End Character	Yes <sup>*2</sup>
Unit No.	1	Station No.	1*2

\*1 Set these parameters in the COM port setup using the Web browser.

\*2 Pass the settings to the task startup FB parameters.

\*3 Communication at 115.2 kbps is possible.



Set the COM port as follows:

Com1SioDriver=DUONUS\_S10

- Com2SioDriver=DUONUS\_S10
- ConsoleComPort=(blank)

STARDOM Standalone Controller FCN/FCJ (When using Yokogawa Electric FCN/FCJ ModbusRTU 1:n Protocol via CPU unit's COM Port connection)

GP Setup		CPU Communication Port Setup	
Baud Rate	9600 bps	Baud Rate	9600 bps *1*3
Data Length	8 bits	Data Length	8 bits <sup>*1</sup>
Stop Bit	1 bit	Stop Bit	1 bit <sup>*1</sup>
Parity Bit	None	Parity Bit	None *1
Data Flow Control	ER Control		
Communication Format	RS-232C		
Station No.	1	Station No.	1 <sup>*2</sup>
		Communication Mode	RTU Mode
		Communication Type	Slave

\*1 Set these parameters in the COM port setup using the Web browser.

\*2 Pass the settings to the task startup FB parameters.

\*3 Communication at 115.2 kbps is possible.



Set the COM port as follows:

Com1SioDriver=DUONUS\_S10

Com2SioDriver=DUONUS\_S10

ConsoleComPort=(blank)

## STARDOM Standalone Controller FCN (When using Yokogawa Electric FCN/FCJ ModbusRTU 1:n Protocol via NFLR111 RS232C Communication Module connection)

GP Setup		NFLR111 Po	rt Setup
Baud Rate	9600 bps	Baud Rate	9600 bps <sup>*1*3</sup>
Data Length	8 bit	Data Length	8 bit <sup>*1</sup>
Stop Bit	1 bit	Stop Bit	1 bit <sup>*1</sup>
Parity Bit	None	Parity Bit	None <sup>*1</sup>
Data Flow Control	ER Control	Other Settings	Use default values <sup>*1</sup>
Communication Format	RS-232C		•
Station No.	1	Station No.	1 <sup>*2</sup>
		Communication Mode	RTU Mode
		Communication Type	Slave

\*1 Set these parameters in the Resource Configurator.

\*2 Pass the settings to the task startup FB parameters.

\*3 Communication at 115.2 kbps is possible.

## STARDOM Standalone Controller FCN (When using Yokogawa Electric FCN/FCJ ModbusRTU 1:n Protocol via NFLR121 RS422/RS485 Communication Module connection)

GP Setup		NFLR121 Port Setup	
Baud Rate	9600 bps <sup>*4</sup>	Baud Rate	9600 bps <sup>*1*3</sup>
Data Length	8 bit	Data Length	8 bit <sup>*1</sup>
Stop Bit	1 bit	Stop Bit	1 bit <sup>*1</sup>
Parity Bit	None	Parity Bit	None <sup>*1</sup>
Data Flow Control	ER Control	Other Settings	Use default values <sup>*1</sup>
Communication	1 wire	viro	1 wiro *1
Format (using 4-wire)	4-10116	Wiring Format	4-wile
Communication	2-wire	ining i onnat	2_wiro *1
Format (using 2-wire)	2 WIIC		2-0016
Station No.	1	Station No.	1 <sup>*2</sup>
			RTU Mode
		Communication Type	Slave

\*1 Set these parameters in the COM port setup using the Web browser.

\*2 Pass the settings to the task startup FB parameters.

\*3 Communication at 115.2 kbps is possible.



When communicating using a 2-wire 1:n connection with 2 or more PLC units, be sure to set the GP unit's Send Wait time of 20ms or more.

If communication is performed using the default value of 0ms, an Host Communication error (02:FE:\*\*) will occur from the PLC.

### Special Settings

#### **Screen Creation Software Settings**

The screen creation software settings are located in the [GP System] - [Mode Settings] area. The screens and items used for entering settings are as follows.

ļ	GP Settings - noname.tmp	ব
	Initial Screen Settings Extended Settings Communication Settings	<u>)</u>
	PLC Type YOKOGAWA FCN/FCJ ModbusRTU 1:n	
	System Start Address	
	Machine Number	
	Read Area Size	
	Link Protocol Type 🎯 1:1 🥥 📶	
	Modbus Config.	++ Designates PLC settings
	OK Cancel Defaults <u>H</u> elp	]



## **Yokogawa Electric**

#### A.1 Maximum Number of Consecutive Device Address

The following lists the maximum number of consecutive addresses that can be read by each PLC. Refer to these tables to utilize *Block Transfer*.



When the device is setup using the methods below, the Data Communication Speed declines by the number of times the device is read.

- When consecutive addresses exceed the maximum data number range
- When an address is designated for *division*
- When device types are different

To speed up data communication, plan the tag layout in screen units, as consecutive devices. (Includes the Alarm and Trend screens.)

## ■ PLC Units

<FACTORY ACE Series>

Device	Max. No. of Consecutive Address	Device	Max. No. of Consecutive Address
Input Relay X	1 Wordo	Timer (current value) TP	
Output Relay Y	- i words	Timer (setup v alue) TS	
Internal Relay I	63 Words	C ounter (current value) C P	
Joint Relay E		C ounter (setup v alue) C S	63 Words
Timer (contact) T	16 Words	Data Register D	
Counter (contact) C		Common Register B <sup>*1</sup>	
Special Relay M	63 Words	File Register B <sup>*1</sup>	
Link Relay L	05 Words	Special Register Z	
		Link Register W	

\*1 Device B becomes the Common Register when the CPU is FA500, and becomes the File Register when the CPU is FA-M3.

<STARDOM Standalone Controller FCN/FCJ Series> (When using Yokogawa Electric FCN/FCJ ModbusRTU 1:n Protocol)

Device	Max. No. of Consecutive Addresses
Coil (0)	
Input Relay (1)	125 Words
Retain Register (4)	125 Words
Input Register (3)	]

## **♦**Ethernet Communication

#### <FACTORY ACE Series/FA-M3>

Device	Max.No.of Consecutive Addresses
Input Relay	1 Word
Output Relay	1 Word
Internal Relay	
Common Relay	64 words
Special Relay	
Link Relay	
Timer (contact)	16 words
Counter (contact)	
Timer (current value)	
Counter (current value)	
Timer (setup value)	
Counter (setup value)	
Data Register	64w ords
File Register	
Common Register	
Special Register	
Link Register	

## Controller

<UT2000/UT3000/Green Series>

Device	Max. No. of Consecutive Address
D	63 Words
I	63 Words

<UT100>

Device	Max. No. of Consecutive	
	Address	
D Register	32 Words	

#### Device Codes and Address Codes

Device codes and address codes are used to specify indirect addresses for the E-tags or K-tags.

The word addresses of data to be displayed are coded and stored in the word address specified by the E-tags and K-tags. (Code storage is done either by the PLC, or with T-tag and K-tags)

## PLCs

A.2

<FA500 (1:1 communication)\*>

	Device	Word Address	Device code (HEX)	Address code
	Input Relay	X00201~	Х	Х
Bit Device	Output Relay	Y00201~	Х	Х
	Internal Relay	10001~	9000	Save as word address value minus 1 divided by 16.
	Joint Relay	E0001~	B800	Save as word address value minus 1 divided by 16.
	Special Relay	M001~ B000		Save as word address value minus 1 divided by 16.
	Link Relay	L0001~	C 000	Save as word address value minus 1 divided by 16.
	Timer (current value)	TP001~	6000	Save as word address value minus 1.
	Timer (set velue)	TS001~	6800	Save as word address value minus 1.
	Coutner (current value)	CP001~	7000	Save as word address value minus 1.
Word	Counter (set value)	CS001~	7800	Save as word address value minus 1.
Device	Data Register	D0001~	0000	Save as word address value minus 1.
	Common Register	B0001~	2000	Save as word address value minus 1.
	Special Register	Z001~	5000	Save as word address value minus 1.
	Link Register	W0001~	5800	Save as word address value minus 1.
	LS area	LS0000~	4000	Word Address

\* Only CPU No. 1 is available.

	Device	Word Address	Device code (HEX)	Address code
	Input Relay	X00201~	Х	Х
	Output Relay	Y00201~	Х	Х
	Internal Relay	10001~	9000	Save as word address value minus 1 divided by 16.
Bit Device	Joint Relay	E0001~	B800	Save as word address value minus 1 divided by 16.
	Special Relay	M001~	B000	Save as word address value minus 1 divided by 16.
	Link Relay	L0001~	C 000	Save as word address value minus 1 divided by 16.
	Timer (current value)	TP001~	6000	Save as word address value minus 1.
	Timer (set velue)	TS001~	6800	Save as word address value minus 1.
	Coutner (current value)	CP001~	7000	Save as word address value minus 1.
Word	Counter (set value)	CS001~	7800	Save as word address value minus 1.
Device	Data Register	D0001~	0000	Save as word address value minus 1.
	Common Register	B0001~	2000	Save as word address value minus 1.
	Special Register	Z001~	5000	Save as word address value minus 1.
	Link Register	W0001~	5800	Save as word address value minus 1.
	LS area	LS0000~	4000	Word Address

<FA500 (1:n communication)\*>

\* Only CPU No. 1 in station No.1 is available.

Device	Device Address	Device code	Address Code
1_0	1_000001 -	1_000001 - 0xB000	
2_0	2_000001 -	0xB200	
3_0	3_000001 -	0xB400	
4_0	4_000001 -	0xB600	
5_0	5_000001 -	0xB800	
6_0	6_000001 -	0xBA00	
7_0	7_000001 -	0xBC00	
8_0	8_000001 -	0xBE00	
9_0	9_000001 -	0xC000	
10_0	10_000001 -	0xC200	
11_0	11_000001 -	0xC400	
12_0	12_000001 -	0xC600	
13_0	13_000001 -	0xC800	
14_0	14_000001 -	0xCA00	
15_0	15_000001 -	0xCC00	
16_0	16_000001 -	0xCE00	(Word Address)/16
17_0	17_000001 -	0x8000	
18_0	18_000001 -	0x8200	
19_0	19_000001 -	0x8400	
20_0	20_000001 -	0x8600	
21_0	21_000001 -	0x8800	
22_0	22_000001 -	0x8A00	
23_0	23_000001 -	0x8C00	
24_0	24_000001 -	0x8E00	
25_0	25_000001 -	25_000001 - 0xD000	
26_0	26_000001 -	0xF200	
27_0	27_000001 -	0xF400	
28_0	28_000001 -	0xF600	
29_0	29_000001 -	0xF800	
30_0	30_000001 -	0xFA00	
31_0	31_000001 -	0xFC00	
1_1	1_100001 -	0x9000	
2_1	2_100001 -	0x9200	
3_1	3_100001 -	0x9400	
4_1	4_100001 -	0x9600	
5_1	5_100001 -	0x9800	(Word Address)/16
6_1	6_100001 -	0x9A00	
7_1	7_100001 -	0x9C00	
8_1	8_100001 -	0x9E00	
9_1	9_100001 -	0xA000	
10_1	10_100001 -	0xA200	

<STARDOM Standalone Controller FCN/FCJ Series> (When using Yokogawa Electric FCN/FCJ ModbusRTU 1:n Protocol)

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## Appendix

11_1	11_100001 -	0xA400		
12_1	12_100001 -	0xA600		
13_1	13_100001 -	0xA800		
14_1	14_100001 -	0xAA00		
15_1	15_100001 -	0xAC00		
16_1	16_100001 -	0xAE00		
17_1	17_100001 -	0x6000		
18_1	18_100001 -	0x6200		
19_1	19_100001 -	0x6400		
20_1	20_100001 -	0x6600		
21_1	21_100001 -	0x6800		
22_1	22_100001 -	0x6A00		
23_1	23_100001 -	0x6C00		
24_1	24_100001 -	0x6E00		
25_1	25_100001 -	0x7000		
26_1	26_100001 -	0x7200		
27_1	27_100001 -	0x7400		
28_1	28_100001 -	0x7600		
29_1	29_100001 -	0x7800		
30_1	30_100001 -	0x7A00		
31_1	31_100001 -	0x7C00		
1_4	1_400001 -	0xD200		
2_4	2_400001 -	0xD400		
3_4	3_400001 -	0xD600		
4_4	4_400001 -	0xD800		
5_4	5_400001 -	0xDA00		
6_4	6_400001 -	0xDC00		
7_4	7_400001 -	0xDE00		
8_4	8_400001 -	0xE000		
9_4	9_400001 -	0xE200		
10_4	10_400001 -	0xE400		
11_4	11_400001 -	0xE600	Word Address - 1	
12_4	12_400001 -	0xE800		
13_4	13_400001 -	0xEA00		
14_4	14_400001 -	0xEC00		
15_4	15_400001 -	0xEE00		
16_4	16_400001 -	0xF000		
17_4	17_400001 -	0x4200		
18_4	18_400001 -	0x4400		
19_4	19_400001 -	0x4600		
20_4	20_400001 -	0x4800		
21_4	21_400001 -	0x4A00		
22_4	22_400001 -	0x4C00		

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23 /	22 /00001	0,400	
23_4	23_400001-	0X4E00	
24_4	24_400001 -	24_400001 - 0x5000	
25_4	25_400001 -	0x5200	
26_4	26_400001 -	0x5400	
27_4	27_400001 -	0x5600	
28_4	28_400001 -	0x5800	
29_4	29_400001 -	0x5A00	
30_4	30_400001 -	0x5C00	
31_4	31_400001 -	0x5E00	
1_3	1_300001 -	0x2000	
2_3	2_300001 -	0x2200	1
3_3	3_300001 -	0x2400	1
4_3	4_300001 -	0x2600	1
5_3	5_300001 -	0x2800	1
6_3	6_300001 -	0x2A00	1
7_3	7_300001 -	0x2C00	
8_3	8_300001 -	0x2E00	1
9_3	9_300001 -	0x3000	
10_3	10_300001 -	0x3200	
11_3	11_300001 -	0x3400	
12_3	12_300001 -	0x3600	
13_3	13_300001 -	0x3800	
14_3	14_300001 -	0x3A00	
15_3	15_300001 -	0x3C00	
16_3	16_300001 -	0x3E00	Word Address - 1
17_3	17_300001 -	0x0200	
18_3	18_300001 -	0x0400	
19_3	19_300001 -	0x0600	
20_3	20_300001 -	0x0800	
21_3	21_300001 -	0x0A00	
22_3	22_300001 -	0x0C00	
23_3	23_300001 -	0x0E00	
24_3	24_300001 -	0x1000	
25_3	25_300001 -	0x1200	
26_3	26_300001 -	0x1400	
27_3	27_300001 -	0x1600	ļ
28_3	28_300001 -	0x1800	ļ
29_3	29_300001 -	0x1A00	ļ
30_3	30_300001 -	0x1C00	ļ
31_3	31_300001 -	0x1E00	
LS Area	LS0000 -	0x4000	Word Address

	Device	Word Address	Device code (HEX)	Address code
	Input Relay	X00201~	Х	Х
	Output Relay	Y00201~	Х	Х
	Internal Relay	10001~	9000	Save as word address value minus 1 divided by 16.
Bit Device	Joint Relay	E0001~	B800	Save as word address value minus 1 divided by 16.
	Special Relay	M0001~	B000	Save as word address value minus 1 divided by 16.
	Link Relay	L00001~	C 000	Save as word address value minus 1 divided by 16.
	Timer (current value)	TP0001~	6000	Save as word address value minus 1.
	Timer (set velue)	TS0001~	6800 Save as word address value minus 1.	
	Coutner (current value)	CP0001~	7000 Save as word address value minus 1	
	Counter (set value)	CS0001~	7800	Save as word address value minus 1.
	Data Register	D0001~	0000	Save as word address value minus 1.
Word		B00001~	2000	Save as word address value minus 1.
Device	Filo Dogistor	B65537~	2800	Save as word address value minus 65537.
		B131073~	1000	Save as word address value minus 131073.
		B196609~	1800	Save as word address value minus 196609.
	Joint Register	R0001~	0800	Save as word address value minus 1.
	Special Register	Z001~	5000	Save as word address value minus 1.
	Link Register	W00001~	5800	Save as word address value minus 1.
	LS area	LS0000~	4000	Word Address

<FA-M3 (1:1 communication)\*>

\* Only CPU No. 1 is available.

	Device Word Address Device code (HEX)		Address code	
	Input Relay	X00201~	Х	Х
	Output Relay	Y00201~	Х	Х
	Internal Relay	100001~	9000	Save as word address value minus 1 divided by 16.
Bit Device	Joint Relay	E0001~	B 800	Save as word address value minus 1 divided by 16.
	Special Relay	M0001~	B000	Save as word address value minus 1 divided by 16.
	Link Relay	L00001~	C 000	Save as word address value minus 1 divided by 16.
	Timer (current value)	TP0001~	6000	Save as word address value minus 1.
	Timer (set velue)	TS0001~	6800	Save as word address value minus 1.
	Coutner (current value)	CP0001~	7000	Save as word address value minus 1.
	Counter (set value)	CS0001~	7800	Save as word address value minus 1.
Word	Data Register	D0001~	0000	Save as word address value minus 1.
Device	File Register	B0001~	2000	Save as word address value minus 1.
	Joint Register	R0001~	0800	Save as word address value minus 1.
	Special Register	Z001~	5000	Save as word address value minus 1.
	Link Register	W0001~	5800	Save as word address value minus 1.
	LS area	LS0000~	4000	Word Address

<FA-M3 (1:n communication)\*>

\* Only CPU No. 1 in station No. 1 is available.

	Device	Word Address	Device code (HEX)	Address code
	Input Relay	X00201~	Х	Х
	Output Relay	Y00201~	Х	Х
	Internal Relay	100001~	9000	Save as word address value minus 1 divided by 16.
Bit Device	Joint Relay	E0001~	B800	Save as word address value minus 1 divided by 16.
	Special Relay	M0001~	B000	Save as word address value minus 1 divided by 16.
	Link Relay	L00001~	C 000	Save as word address value minus 1 divided by 16.
	Timer (current value)	TP0001~	6000	Save as word address value minus 1.
	Timer (set velue)	TS0001~	6800	Save as word address value minus 1.
	Coutner (current value)	CP0001~	7000	Save as word address value minus 1.
	Counter (set value)	CS0001~	7800	Save as word address value minus 1.
	Data Register	D0001~	0000	Save as word address value minus 1.
Word	Filo Dogistor	B0001~	2000	Save as word address value minus 1.
Device		B65537~	2800	Save as word address value minus 65537.
		B131073~	1000	Save as word address value minus 131073.
		B196609~	1800	Save as word address value minus 196609.
	Joint Register	R0001~	0800	Save as word address value minus 1.
	Special Register	Z001~	5000	Save as word address value minus 1.
	Link Register	W0001~	5800	Save as word address value minus 1.
	LS area	LS0000~	4000	Word Address

<FA-M3 (Ethenet communication)\*>

\* Only CPU No. 1 is available

#### **♦** DeviceNet Communication

	Device	Word Address	Device code (HEX)	Address code
Word Device	LS area	LS0000 ~	4000	Word Address

## **Controllers**

#### <UT2000/UT3000/Green Series>

	Device	Word Address	Device Code (HEX)	Address Code
Word Device	D	0001 ~	0000	Word Address -1
Bit Device	I	0001 ~	9000	Save as word address -1 value divided by 16
Word Device	LS Area	LS6000 ~	4000	Woord Address

#### <UT100>

	Device	Word Address	Device Code (HEX)	Address Code
Word Device	D Register	d0001 ~	3000	Word Address -1
	LS Area	LS0000 ~	4000	Word Address

A.3

## Address Conversion Table

		Before Conversion					
		0	1	3	4	LS	
After Conversion	0	0	0	Ο	0	0	
	1	0	0	0	0	0	
	3	0	0	0	0	0	
	4	0	0	0	0	0	
	LS	0	0	0	0	0	

The address conversion table is shown below.

• When the conversion mode is set to "Word", both word and bit devices will be converted. If the conversion mode is set to "Bit", only bit devices will be converted.